

Math

Vector Identities

$$\begin{aligned}
 a \cdot (b \times c) &= b \cdot (c \times a) = c \cdot (a \times b) \\
 a \times (b \times c) &= (a \cdot c)b - (a \cdot b)c \\
 (a \times b) \cdot (c \times d) &= (a \cdot c)(b \cdot d) - (a \cdot d)(b \cdot c) \\
 \nabla \times \nabla \psi &= 0 \\
 \nabla \cdot (\nabla \times a) &= 0 \\
 \nabla \times (\nabla \times a) &= \nabla(\nabla \cdot a) - \nabla^2 a \\
 \nabla \cdot (\psi a) &= a \cdot \nabla \psi + \psi \nabla \cdot a \\
 \nabla \times (\psi a) &= \nabla \psi \times a + \psi \nabla \times a \\
 \nabla(a \cdot b) &= (a \cdot \nabla)b + (b \cdot \nabla)a + a \times (\nabla \times b) + b \times (\nabla \times a) \\
 \nabla \cdot (a \times b) &= b \cdot (\nabla \times a) - a \cdot (\nabla \times b) \\
 \nabla \times (a \times b) &= a(\nabla \cdot b) - b(\nabla \cdot a) + (b \cdot \nabla)a - (a \cdot \nabla)b
 \end{aligned}$$

Vector Calculus Theorems

$$\begin{aligned}
 \int_V \nabla \cdot A \, dV &= \int_S A \cdot n \, dA \quad (\text{Divergence}) \\
 \int_S (\nabla \times A) \cdot n \, dA &= \oint_C A \cdot dl \quad (\text{Stokes})
 \end{aligned}$$

Curvilinear Coordinates

$$\begin{aligned}
 (x, y, z) &\rightarrow h_1 = h_2 = h_3 = 1 \\
 (r, \phi, z) &\rightarrow h_1 = 1 \quad h_2 = r \quad h_3 = 1 \\
 (r, \theta, \phi) &\rightarrow h_1 = 1 \quad h_2 = r \quad h_3 = r \sin \theta
 \end{aligned}$$

$$\begin{aligned}
 ds &= \hat{e}_1 h_1 dx_1 + \hat{e}_2 h_2 dx_2 + \hat{e}_3 h_3 dx_3 \quad dV = h_1 dx_1 h_2 dx_2 h_3 dx_3 \\
 \nabla u &= \hat{e}_1 \frac{1}{h_1} \frac{\partial u}{\partial x_1} + \hat{e}_2 \frac{1}{h_2} \frac{\partial u}{\partial x_2} + \hat{e}_3 \frac{1}{h_3} \frac{\partial u}{\partial x_3} \\
 \nabla \cdot v &= \frac{1}{h_1 h_2 h_3} \left[\frac{\partial}{\partial x_1} (h_2 h_3 v_1) + \frac{\partial}{\partial x_2} (h_1 h_3 v_2) + \frac{\partial}{\partial x_3} (h_1 h_2 v_3) \right] \\
 \nabla \times v &= \frac{1}{h_1 h_2 h_3} \begin{vmatrix} h_1 \hat{e}_1 & h_2 \hat{e}_2 & h_3 \hat{e}_3 \\ \frac{\partial}{\partial x_1} & \frac{\partial}{\partial x_2} & \frac{\partial}{\partial x_3} \\ h_1 v_1 & h_2 v_2 & h_3 v_3 \end{vmatrix}
 \end{aligned}$$

$$\begin{aligned}
 \nabla^2 u &= \nabla \cdot \nabla u \\
 x &= r \cos \phi & y &= r \sin \phi & z &= z \\
 \hat{r} &= \cos \phi \hat{x} + \sin \phi \hat{y} & \hat{\phi} &= -\sin \phi \hat{x} + \cos \phi \hat{y} & \hat{z} &= \hat{z} \\
 \hat{x} &= \cos \phi \hat{r} - \sin \phi \hat{\phi} & \hat{y} &= \sin \phi \hat{r} + \cos \phi \hat{\phi} & \hat{z} &= \hat{z} \\
 x &= r \sin \theta \cos \phi & y &= r \sin \theta \sin \phi & z &= r \cos \theta \\
 \hat{r} &= \sin \theta \cos \phi \hat{x} + \sin \theta \sin \phi \hat{y} + \cos \theta \hat{z} & \hat{\theta} &= \\
 \cos \theta \cos \phi \hat{x} + \cos \theta \sin \phi \hat{y} - \sin \theta \hat{z} & \hat{\phi} &= -\sin \phi \hat{x} + \cos \phi \hat{y} \\
 \hat{x} &= \sin \theta \cos \phi \hat{r} + \cos \theta \cos \phi \hat{\theta} - \sin \phi \hat{\phi} & \hat{y} &= \\
 \sin \theta \sin \phi \hat{r} + \cos \theta \sin \phi \hat{\theta} + \cos \phi \hat{\phi} & \hat{z} &= \cos \theta \hat{r} - \sin \theta \hat{\theta}
 \end{aligned}$$

Series

$$\begin{aligned}
 (1+x)^n &= 1 + nx + \frac{n(n-1)}{2!} x^2 + \frac{n(n-1)(n-2)}{3!} x^3 + \dots \\
 (a+b)^n &= \sum_{k=0}^n \frac{n!}{k!(n-k)!} a^{n-k} b^k \\
 f(a+x) &= f(a) + x f'(a) + \frac{x^2}{2!} f''(a) + \dots \\
 e^x &= \sum_{n=0}^{\infty} \frac{x^n}{n!} = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots \\
 \sin x &= x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots \\
 \cos x &= 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots \\
 \sum_{n=0}^N x^n &= \frac{1-x^{N+1}}{1-x}
 \end{aligned}$$

Complex Analysis

$$\begin{aligned}
 z &= x + iy = r e^{i\theta} = r(\cos \theta + i \sin \theta) \quad f(z) = u(x, y) + iv(x, y) \\
 \text{Cauchy-Riemann: } \frac{\partial u}{\partial x} &= \frac{\partial v}{\partial y} \quad \frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}
 \end{aligned}$$

Residue Calculus

The following methods may be used to calculate the residue of a function $F(z)$ at a singular point z_0 .

1. Expand $F(z)$ in a series about z_0 , and so obtain the coefficient of the term $1/(z - z_0)$. This fundamental method uses the

definition of the residue and is valid for all types of singularities. 2. If the point z_0 is a pole of order m , the residue may be calculated by taking the following limit:

$$R = \lim_{z \rightarrow z_0} \frac{1}{(m-1)!} \frac{d^{m-1}}{dz^{m-1}} [(z - z_0)^m F(z)]$$

3. If the point z_0 is a simple pole, the residue may be calculated by taking the following limit:

$$R = \lim_{z \rightarrow z_0} (z - z_0) F(z)$$

4. If $F(z)$ may be put in the form $F(z) = p(z)/q(z)$ where $q(z_0) = 0$ but $\frac{dq}{dz} \Big|_{z=z_0} \neq 0$, and where $p(z_0) \neq 0$, the residue may be calculated by taking the following limit:

$$R = \lim_{z \rightarrow z_0} \frac{p}{dq/dz}$$

$$\oint_C f(z) dz = 2\pi i \left(\sum \text{residues} \right)$$

Series Summation

$$\begin{aligned}
 \sum_{n=-\infty}^{\infty} (-1)^n f(n) &\rightarrow \oint_C \frac{f(z) dz}{\sin \pi z} \\
 \sum_{n=-\infty}^{\infty} f(n) &\rightarrow \oint_C \frac{\pi f(z)}{\tan \pi z} \\
 \sum_{n=-\infty}^{\infty} f(in) &\rightarrow \oint_C \frac{f(z)}{e^z - 1}
 \end{aligned}$$

Gamma Function

$$\begin{aligned}
 \Gamma(z) &= \int_0^{\infty} e^{-t} t^{z-1} dt \quad \Re(z) > 0 \\
 \Gamma(z+1) &= z\Gamma(z) \\
 \Gamma(n) &= (n-1)!
 \end{aligned}$$

$$\Gamma(z)\Gamma(1-z) = \frac{\pi}{\sin \pi z}$$

Error Propagation

$$\begin{aligned}
 q &= x + \dots + z - (u + \dots + w) \\
 \delta q &= \sqrt{(\delta x)^2 + \dots + (\delta z)^2 + (\delta u)^2 + \dots + (\delta w)^2} \\
 q &= \frac{x \times \dots \times z}{u \times \dots \times w} \\
 \frac{\delta q}{|q|} &= \sqrt{\left(\frac{\delta x}{x}\right)^2 + \dots + \left(\frac{\delta z}{z}\right)^2 + \left(\frac{\delta u}{u}\right)^2 + \dots + \left(\frac{\delta w}{w}\right)^2} \\
 q &= Bx \\
 \delta q &= |B| \delta x \\
 q &= x^n \\
 \frac{\delta q}{|q|} &= |n| \frac{\delta x}{|x|} \\
 q &= q(x, \dots, z) \\
 \delta q &= \sqrt{\left(\frac{\partial q}{\partial x} \delta x\right)^2 + \dots + \left(\frac{\partial q}{\partial z} \delta z\right)^2}
 \end{aligned}$$

Special Functions

$$\begin{aligned}
 \text{Bessel: } e^{(x/2)(t-1/t)} &= \sum_{n=-\infty}^{\infty} J_n(x) t^n \\
 \text{Legendre: } (1-2xt+t^2)^{-1/2} &= \sum_{n=0}^{\infty} P_n(x) t^n \\
 \text{Hermite: } e^{-t^2+2tx} &= \sum_{n=0}^{\infty} H_n(x) \frac{t^n}{n!} \\
 \text{Laguerre: } \frac{e^{-xz/(1-z)}}{1-z} &= \sum_{n=0}^{\infty} L_n(x) z^n
 \end{aligned}$$

Asymptotic Expansion of Integrals

$$\begin{aligned}
 I(x) &= \int_a^b f(t) e^{x\psi(t)} dt \quad x \rightarrow \infty \\
 \text{if } \psi &\text{ has a max at } c, \psi'(c) = 0 \quad a < c < b \\
 \text{then } \psi(t) &= \psi(c) + \underbrace{\psi'(c)(t-c)}_{=0} + \frac{\psi''(c)}{2!} (t-c)^2 + \dots
 \end{aligned}$$

$$\begin{aligned}
 I(x) &\approx \int_a^b f(c) e^{x\psi(c)} e^{x \frac{\psi''(c)}{2!} (t-c)^2} dt \quad \psi''(c) < 0 \text{ for max} \\
 &= \int_{c-\epsilon}^{c+\epsilon} f(c) e^{x\psi(c)} e^{-x \frac{|\psi''(c)|}{2!} (t-c)^2} \\
 &= f(c) e^{x\psi(c)} \int_{-\infty}^{\infty} e^{-x \frac{|\psi''(c)|}{2!} (t-c)^2} dt = \frac{\sqrt{2\pi} f(c) e^{x\psi(c)}}{\sqrt{x |\psi''(c)|}}
 \end{aligned}$$

if the max occurs at the one of the endpoints, it is half of the calculated value

if $\psi(t)$ has no maximum in the interval (a, b) then take the max value to be at endpoint which maximizes $\psi(t)$, notice here that $\psi'(c) \neq 0$ so the second derivative is not needed

Other Useful Things

$$\int_0^\infty e^{-ax^2} dx = \frac{1}{2} \left(\frac{\pi}{a}\right)^{1/2}$$

$$\ln n! \simeq n \ln n - n$$

Fourier Transforms

Trig Identities